

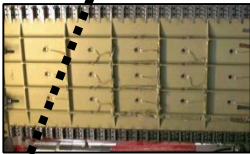
3 M Bolts in Assemblies*



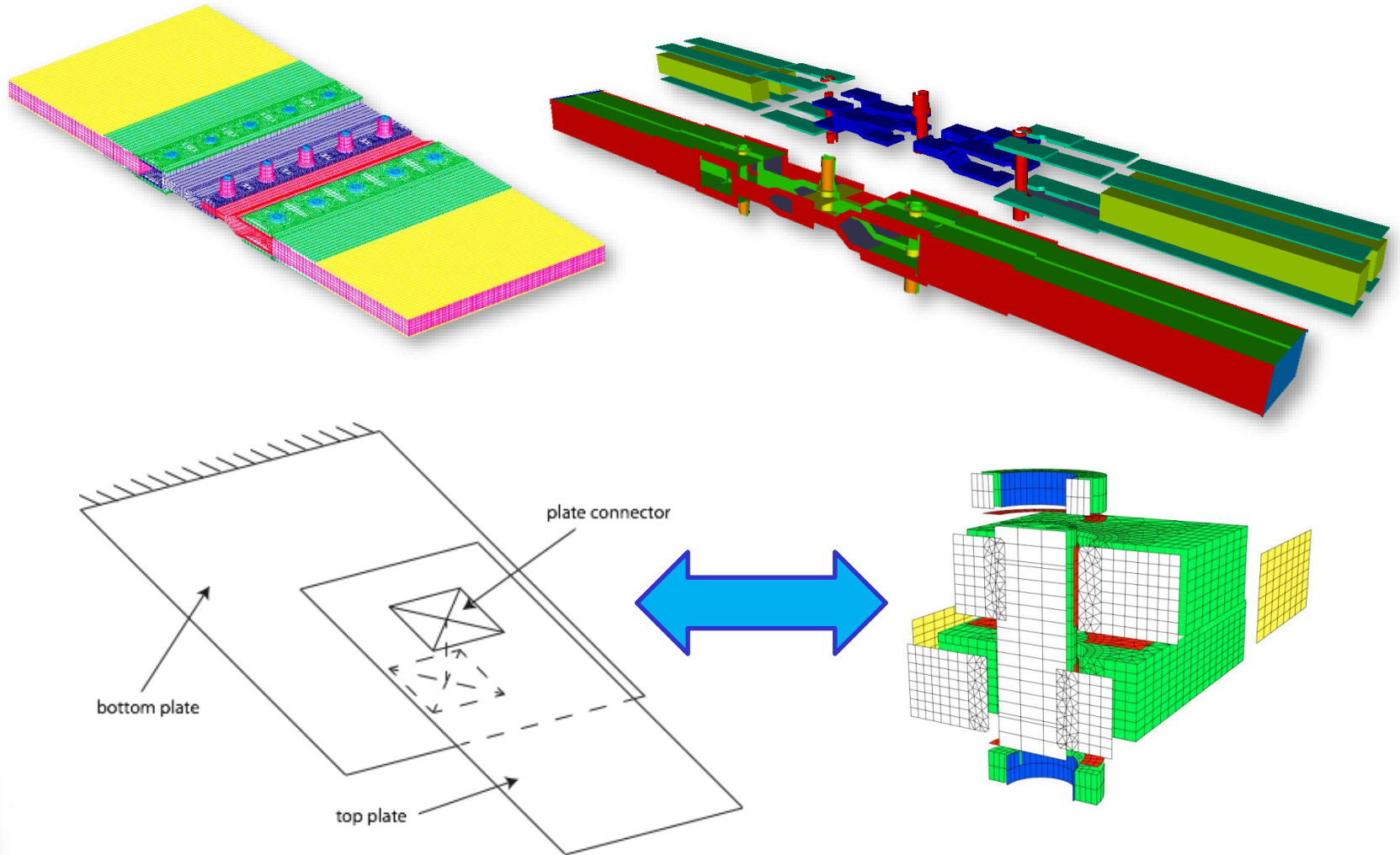
- Reliable control of bonding of composites / maintenance?
- Many parameters influence assembly to transfer load, or to dissipate energy
- Sizing based on finding most loaded bolt
- New experimental tools: image correlation

*[<https://lejournal.cnrs.fr/videos/la-si-delicate-physique-des-trous>]

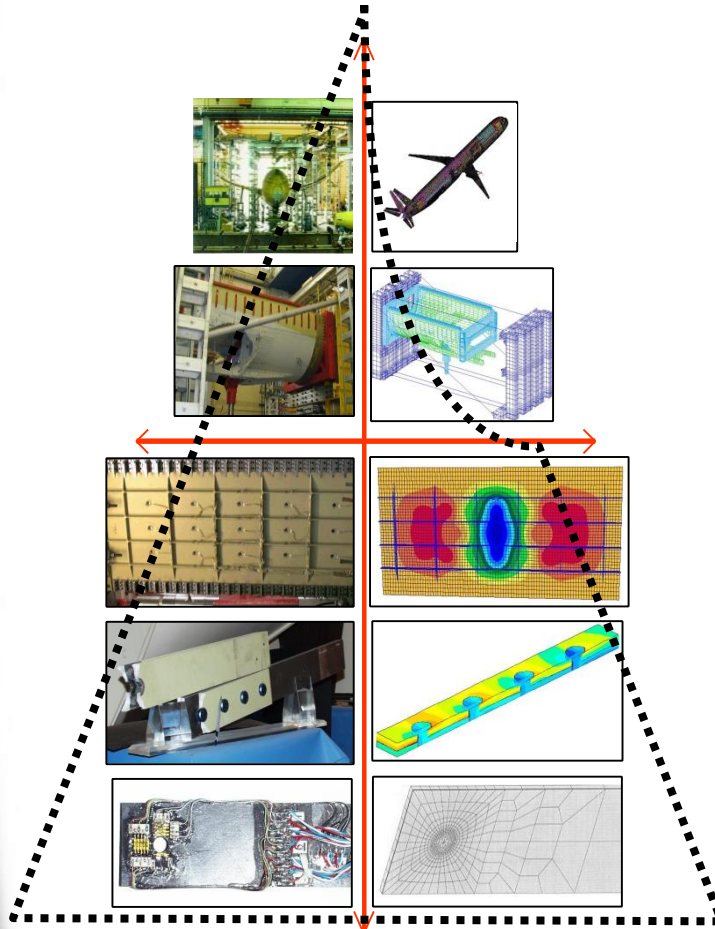
Test Pyramid



Multiscale Modeling of Bolted Assemblies



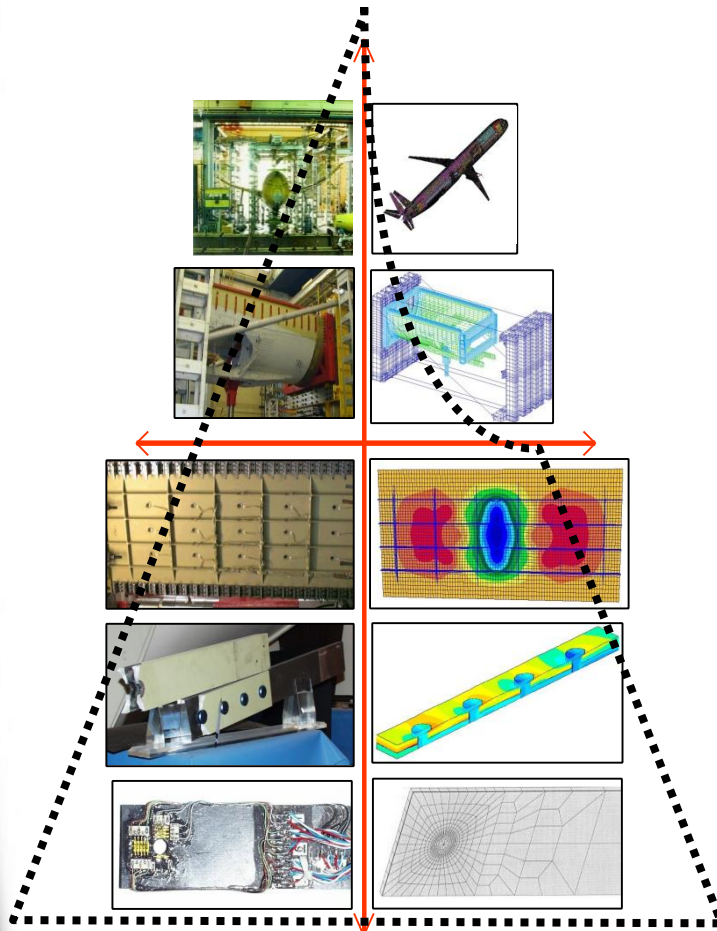
Test and Simulation Pyramid



Tests

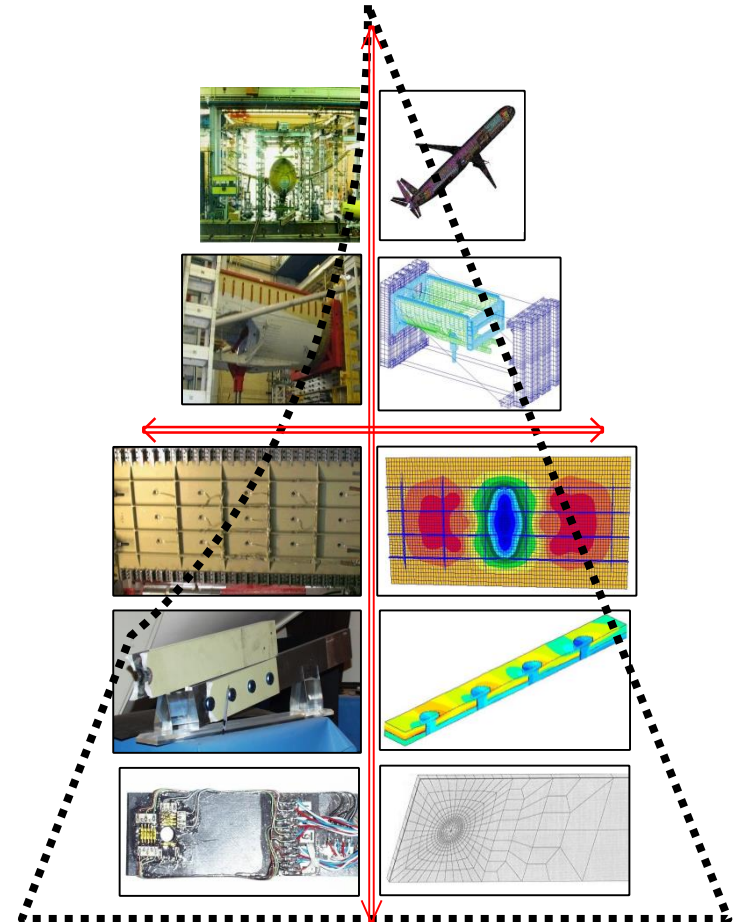
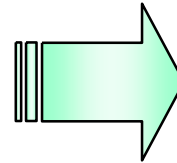
Simulations

Toward Virtual Tests?



Tests

Simulations

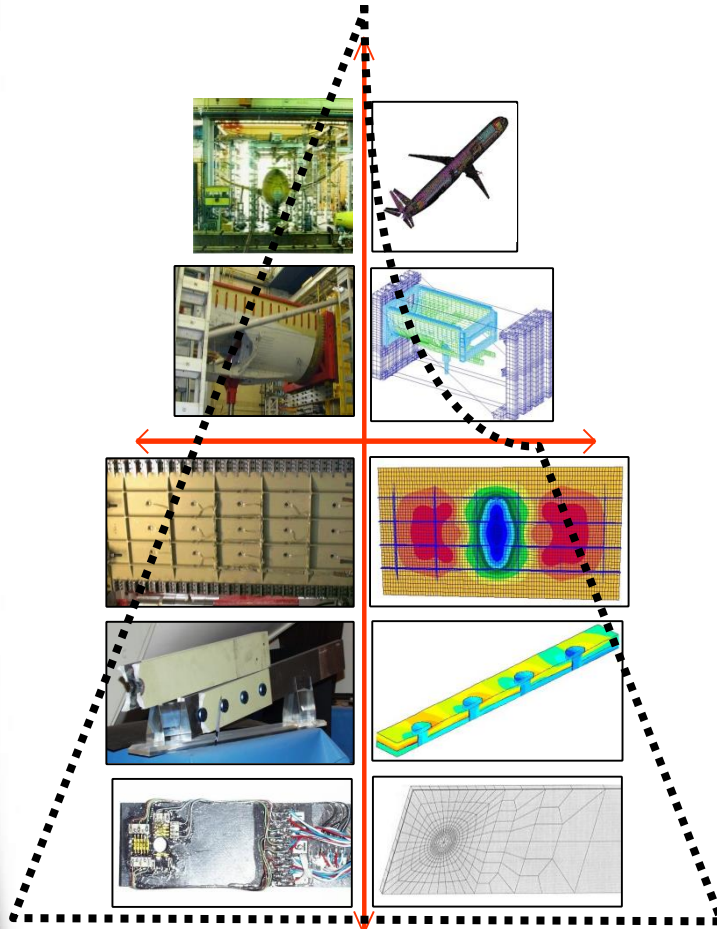


*[Mahé et al., 2005, 7^e CNCS]

[Structures et tremblements, 2005, J. CNRS, 184]

[Barbaux, 2011, Journées UPSTI]

Bolted Assemblies?



Tests

Simulations

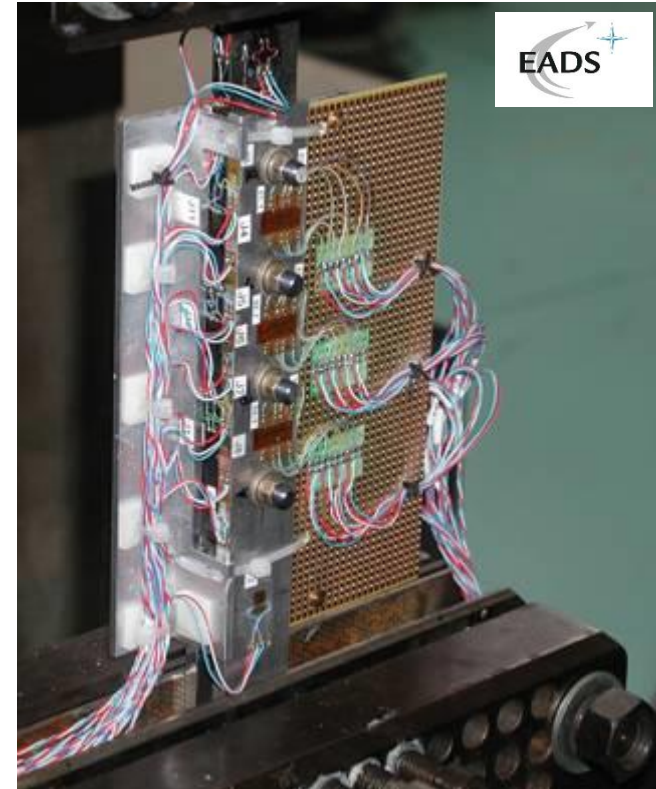
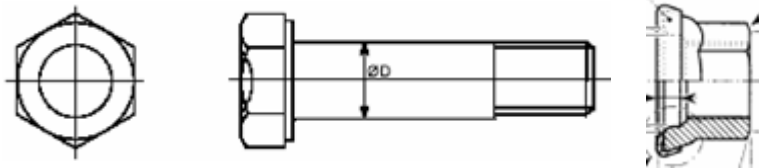
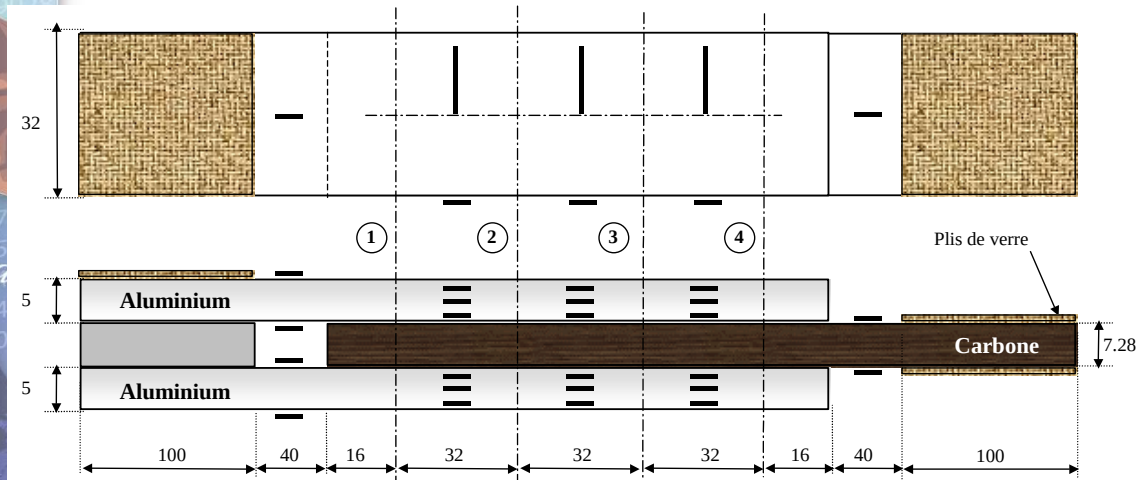
Challenges:

Mechanical stresses + thermal stresses (difference between coefficients of thermal expansion) + assembly stresses

→ Improved understanding of load transfers during the life cycle of an aircraft for **optimized** sizing

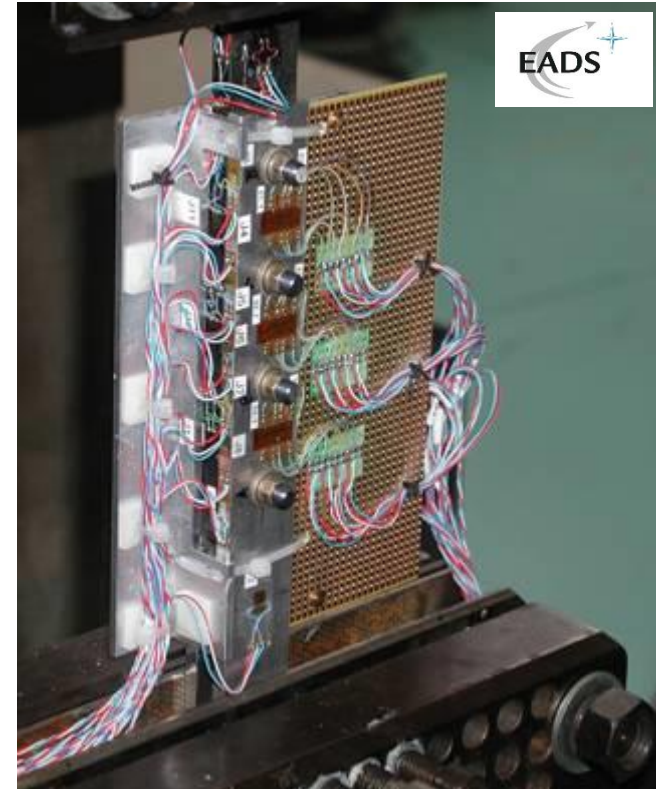
Background

Case study: Standard method



Challenges

- Discriminate and quantify load transfer modes
- Minimize instrumentation cost
- Reliability of measurements
- Identification of characteristic parameters (e.g., rigidity, coefficient of friction)
- Comparisons between test and computation

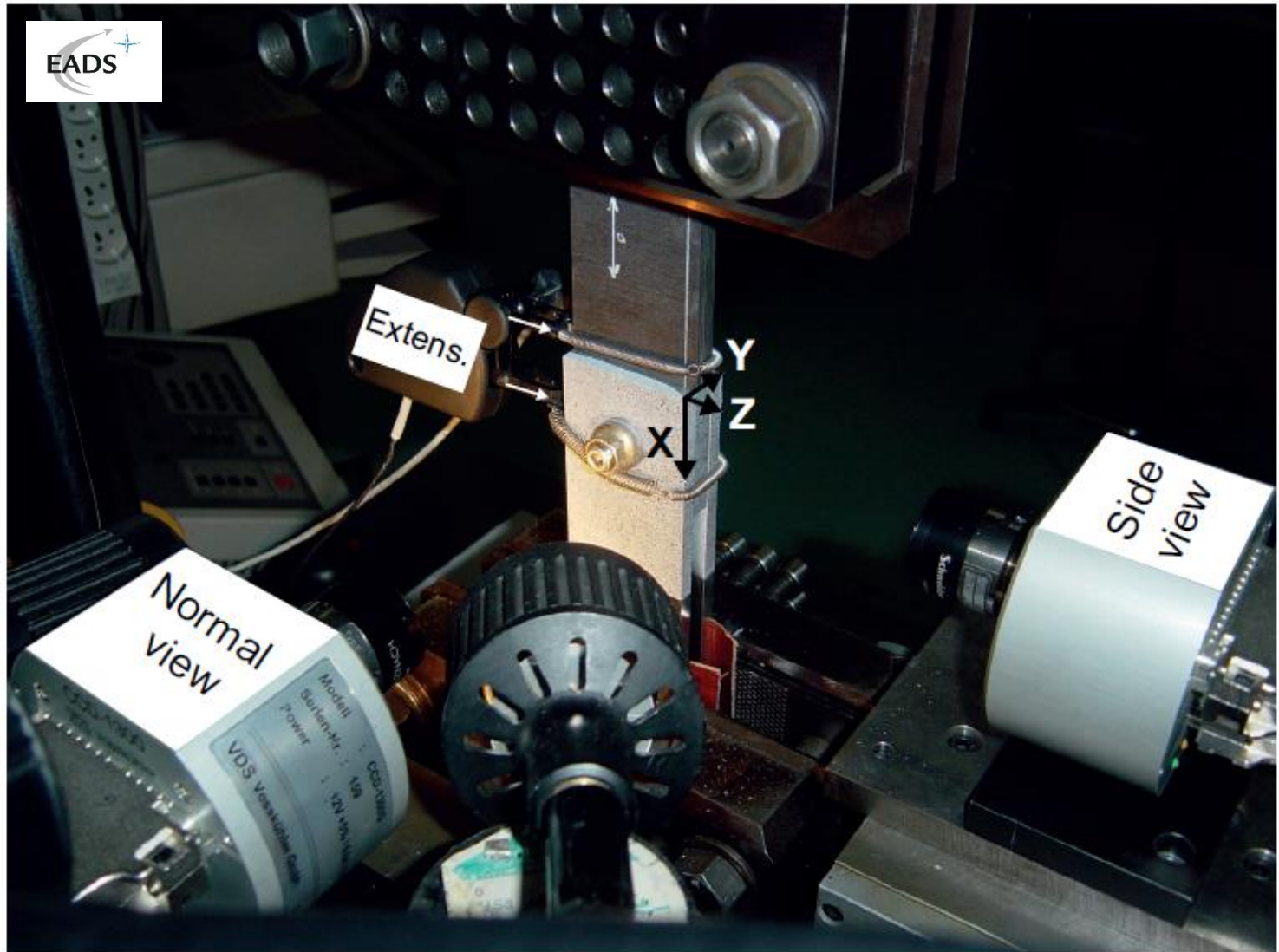


Outline

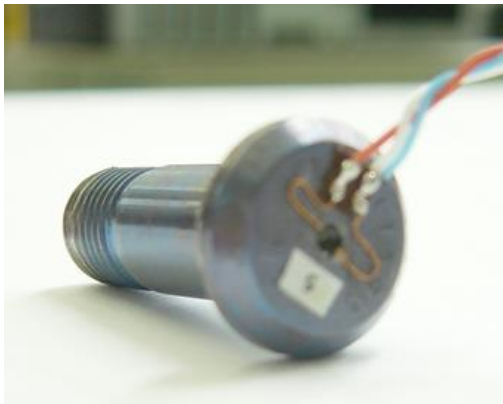
- Introduction
- **Double lap joint w/ single bolt (fatigue)**
- Load transfer in 4-bolt assembly
- Conclusion & perspectives



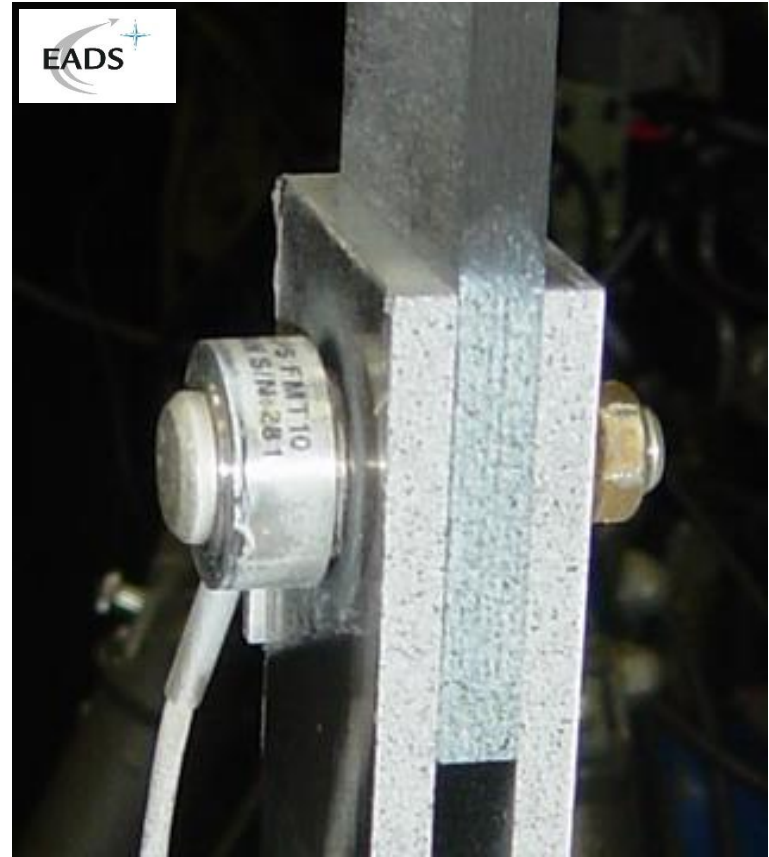
Experimental Protocol



Bolt Load Cell



Bolt Load Cell





Studied Assemblies

Hybrid assembly (DLS):

- 2 Al alloy plates (2024)
- 1 carbon / epoxy composite plate (32 plies)

3 configurations:

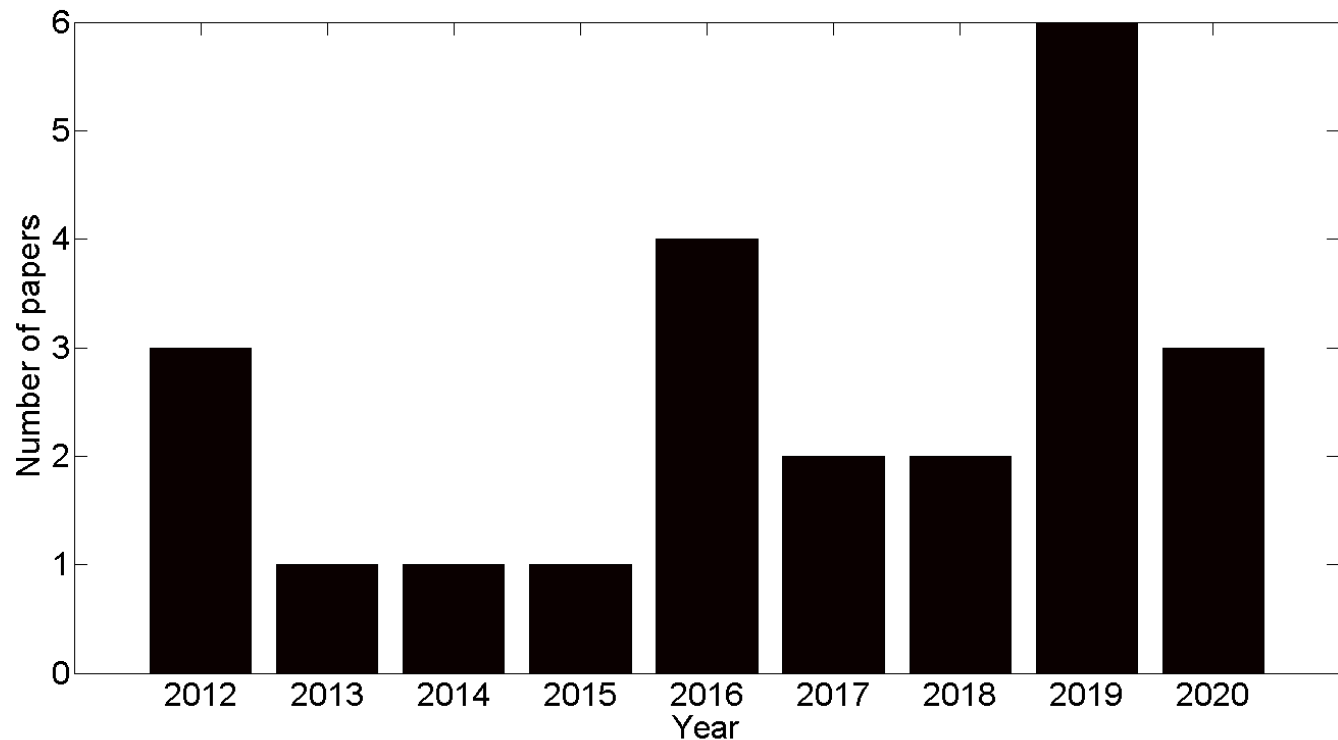
- Reference
- Severe (sandblasted)
- Reduced bolt tension (30%)

2 methods (DIC):

- Discrete
- 2D fields

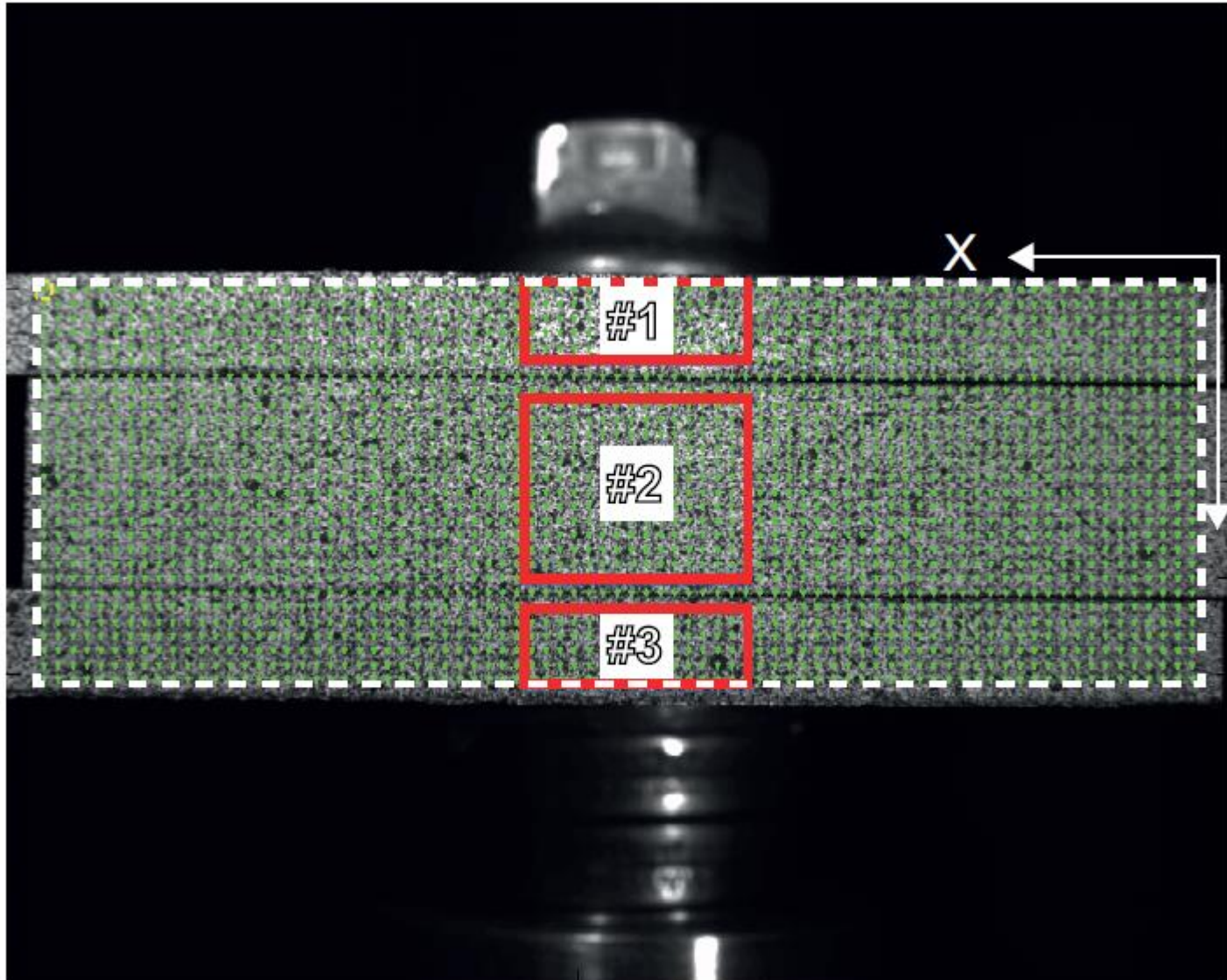
How Classical?

Topic*: “digital image correlation” & “friction coefficient”



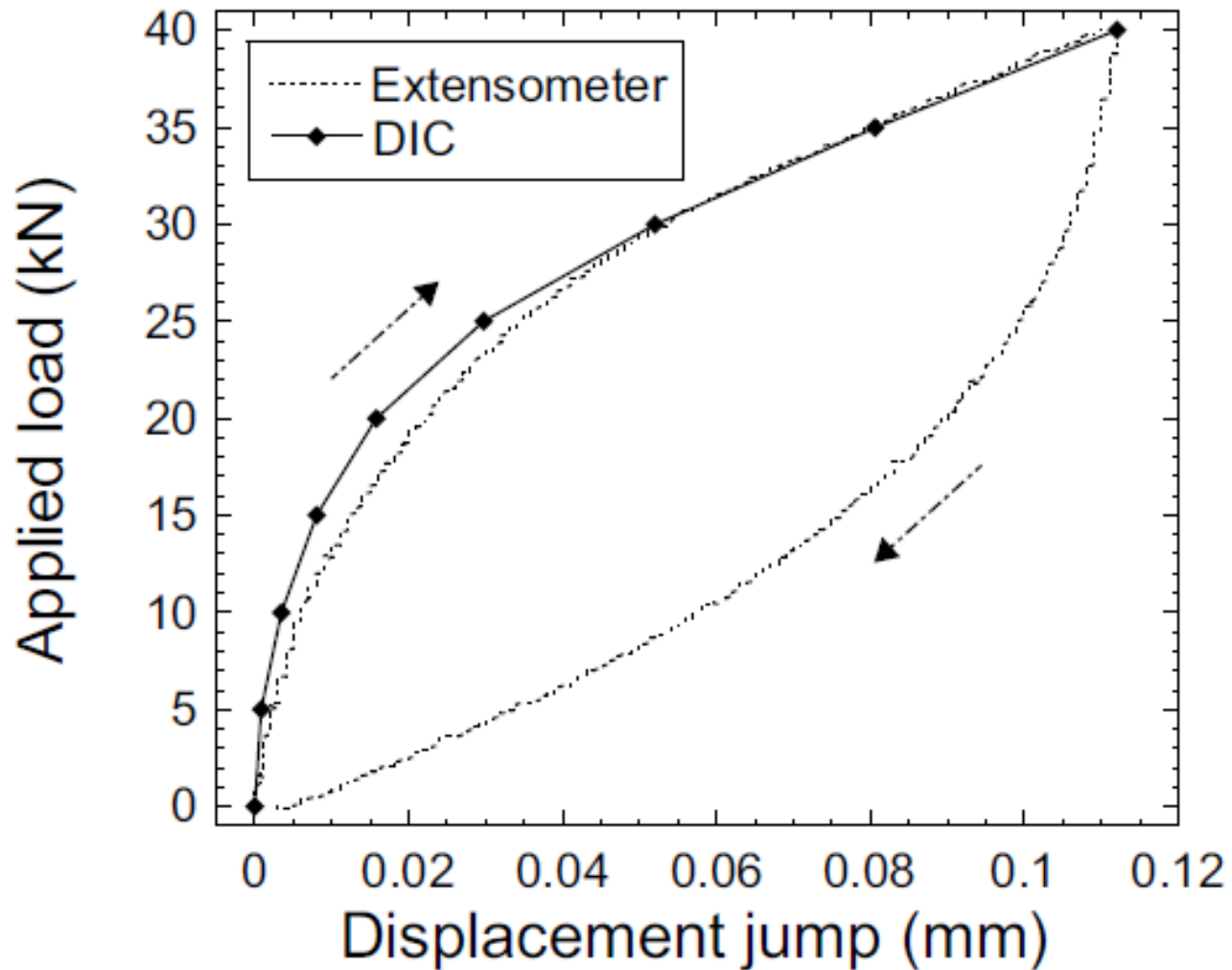
*[Web of Science, accessed on January 21, 2021]

Analysis of Edge

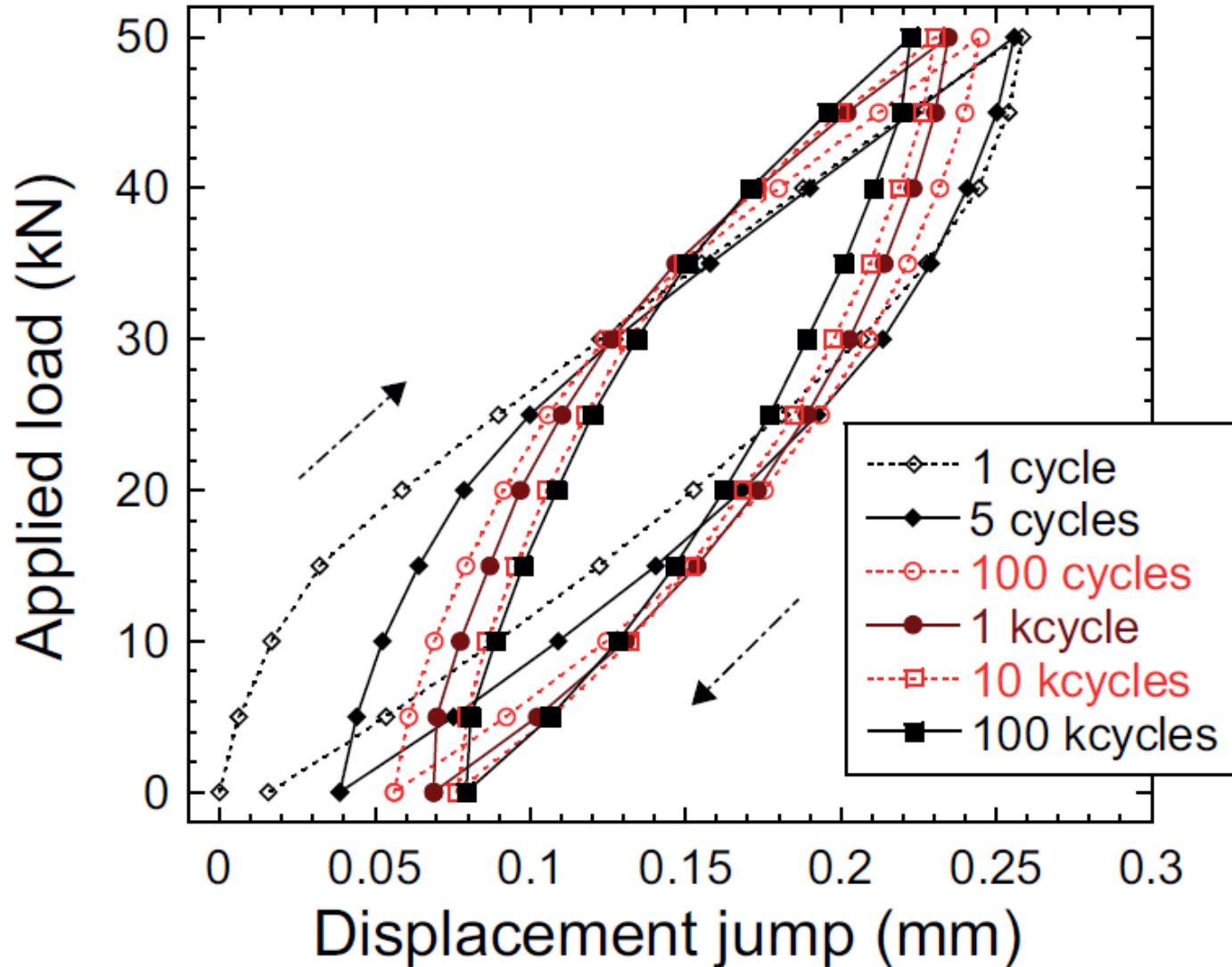


Comparison w/ extensometer

First cycle

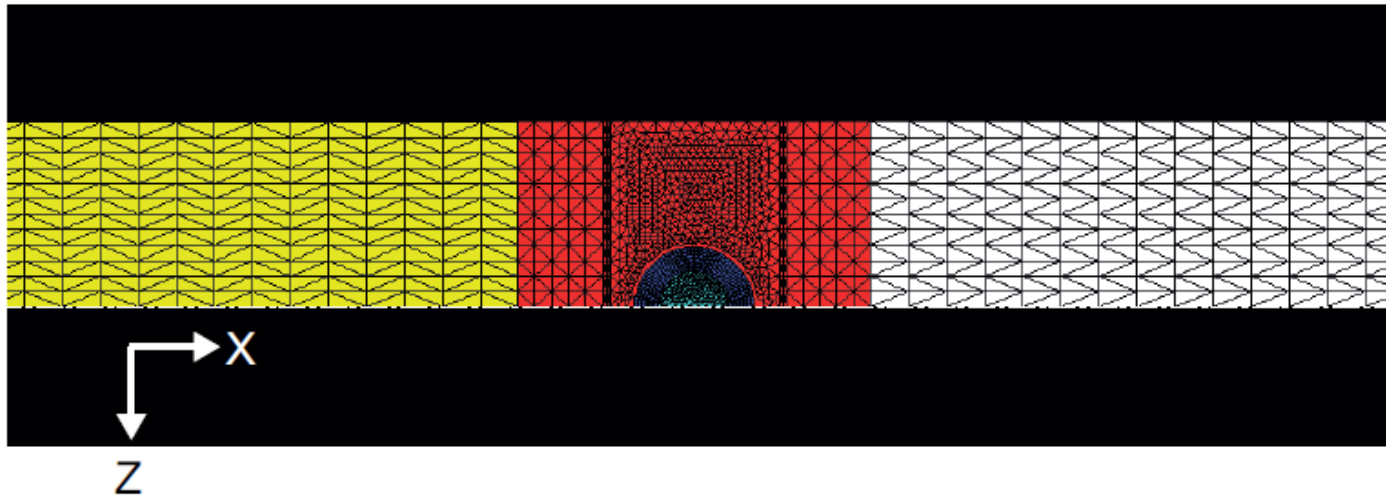
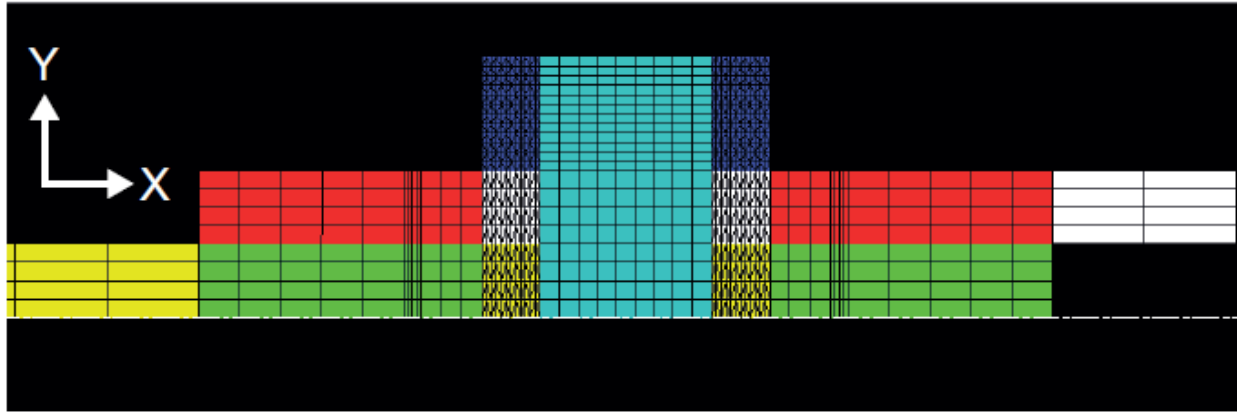


Changes w/ Number of Cycles



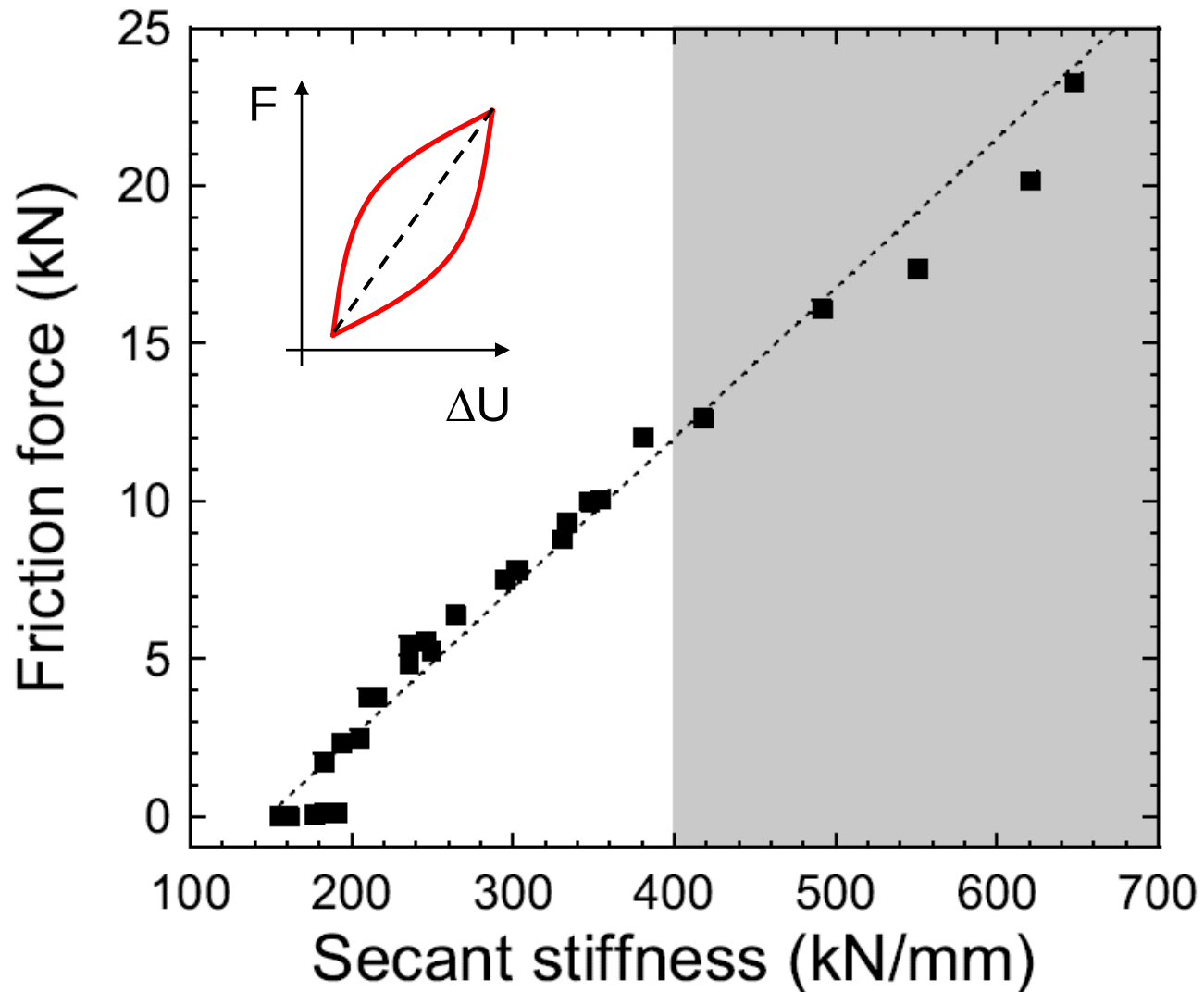
Numerical Model (Cofast*)

Constant Gap + 3D Friction + Symmetry

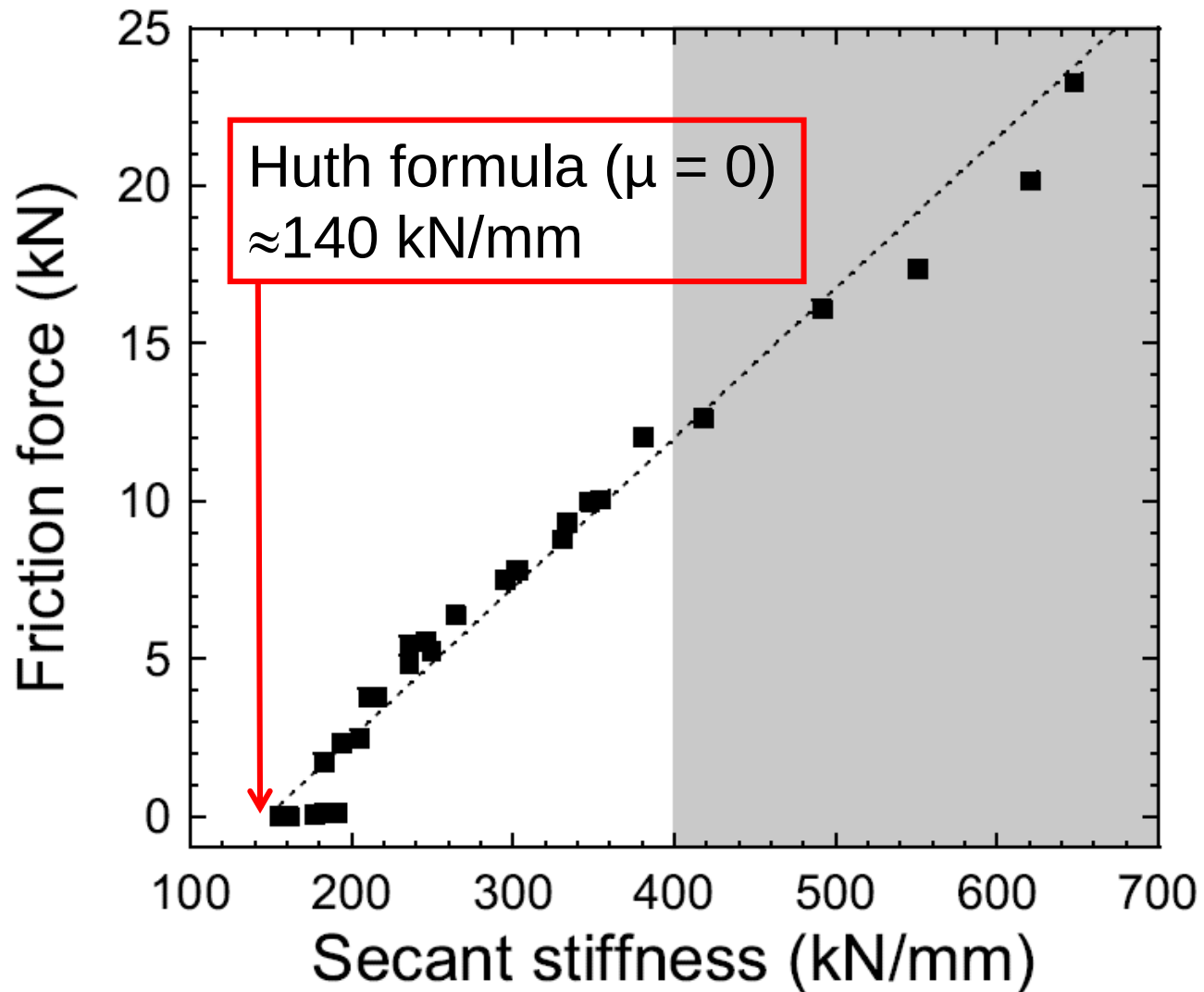


*[Champaney et al., 2008, *Comput. Mech.* 42 pp. 305-315]

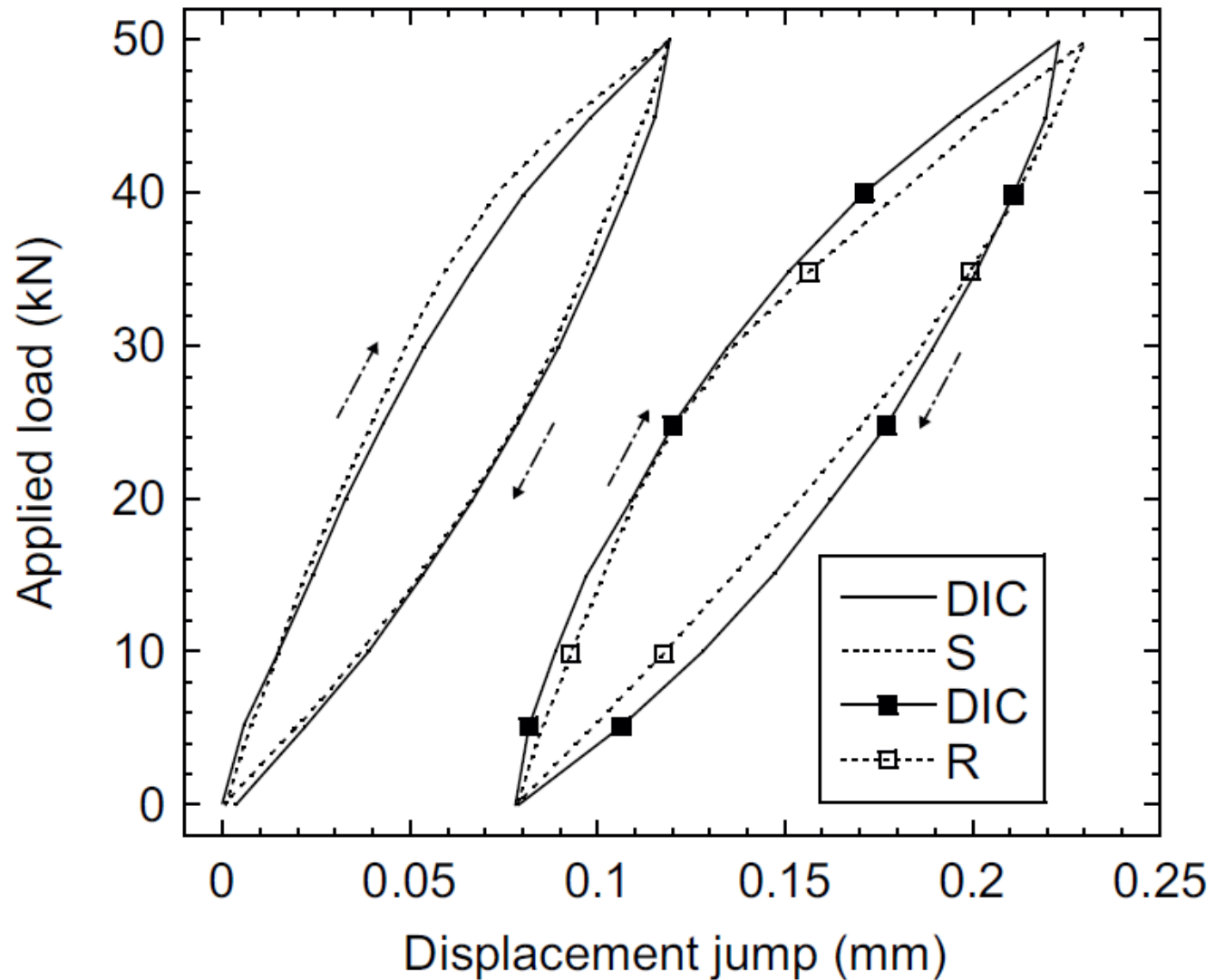
Secant Stiffness (Simulation): Good Indicator



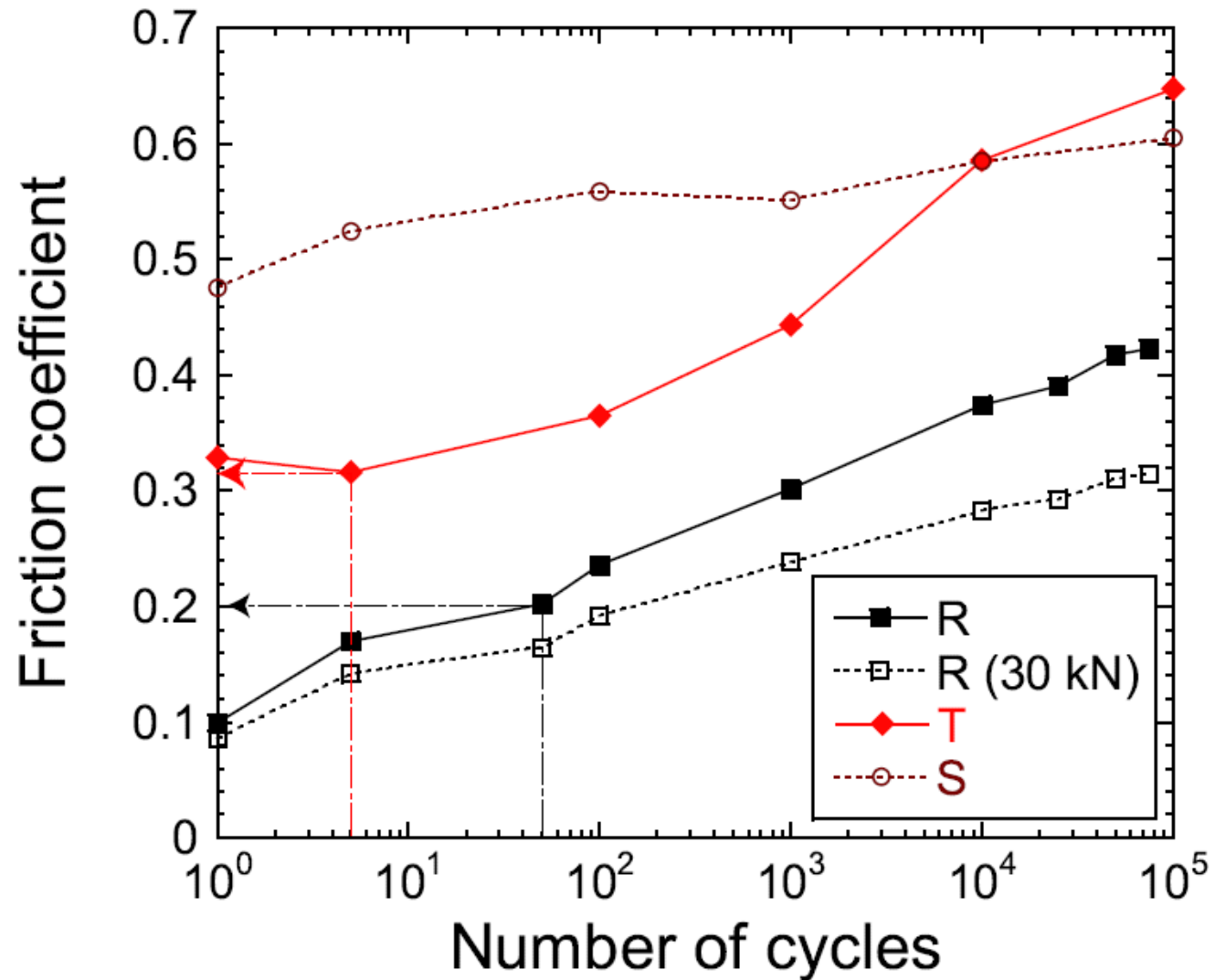
Secant Stiffness (Simulation): Good Indicator



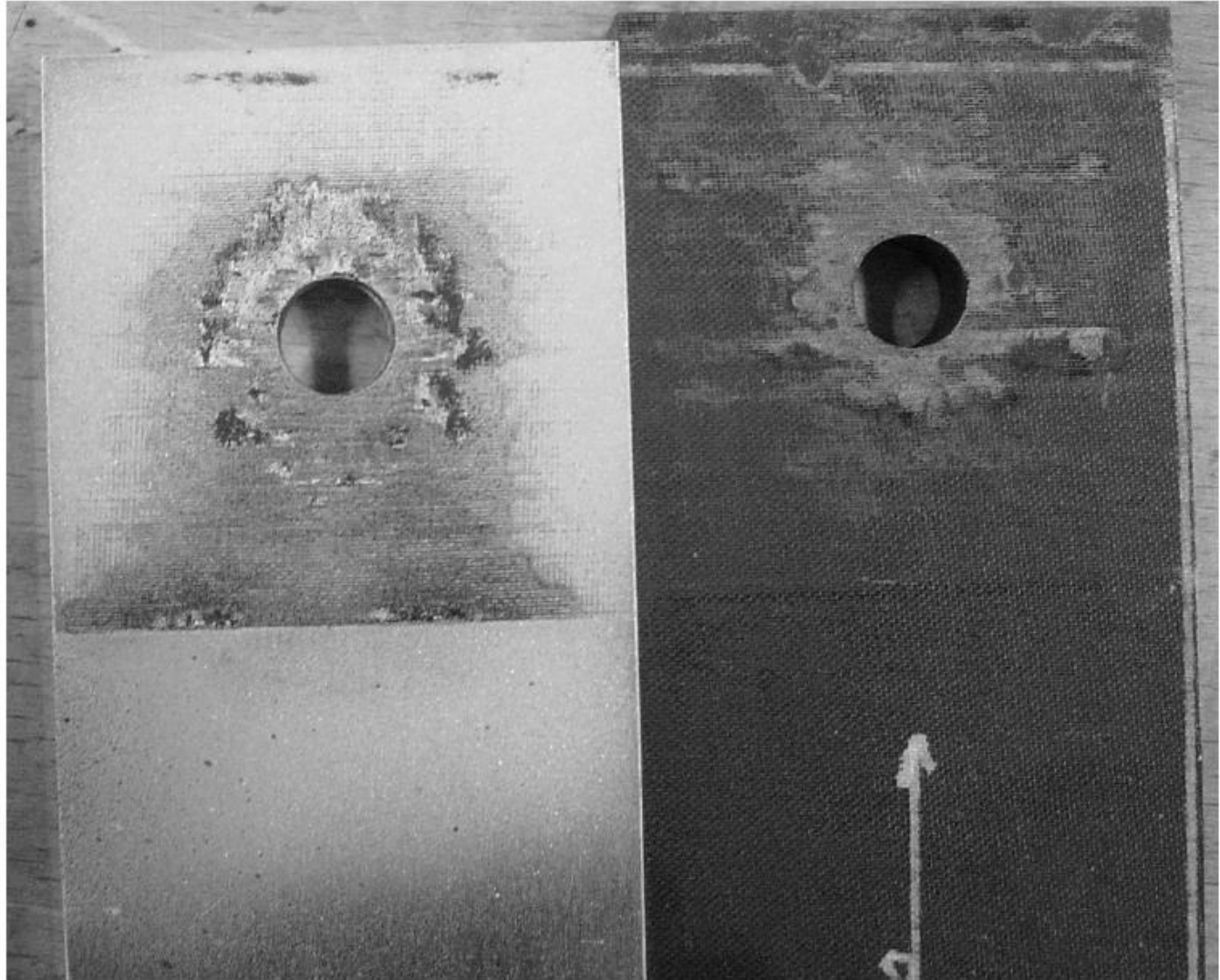
Identification Results



Identification of Friction Coefficient (vs. Number of Cycles)



Post-mortem Observations (T)

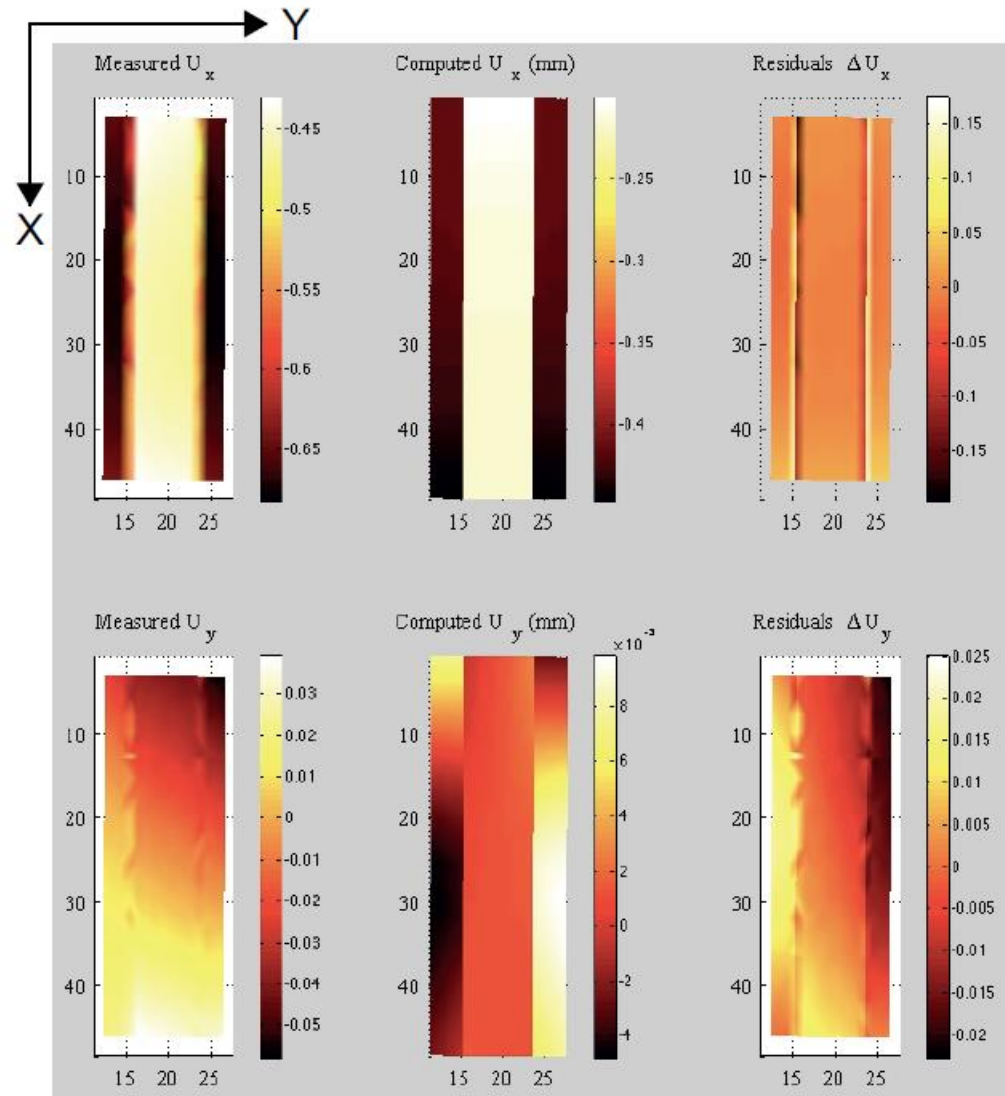


Full-Field Validation

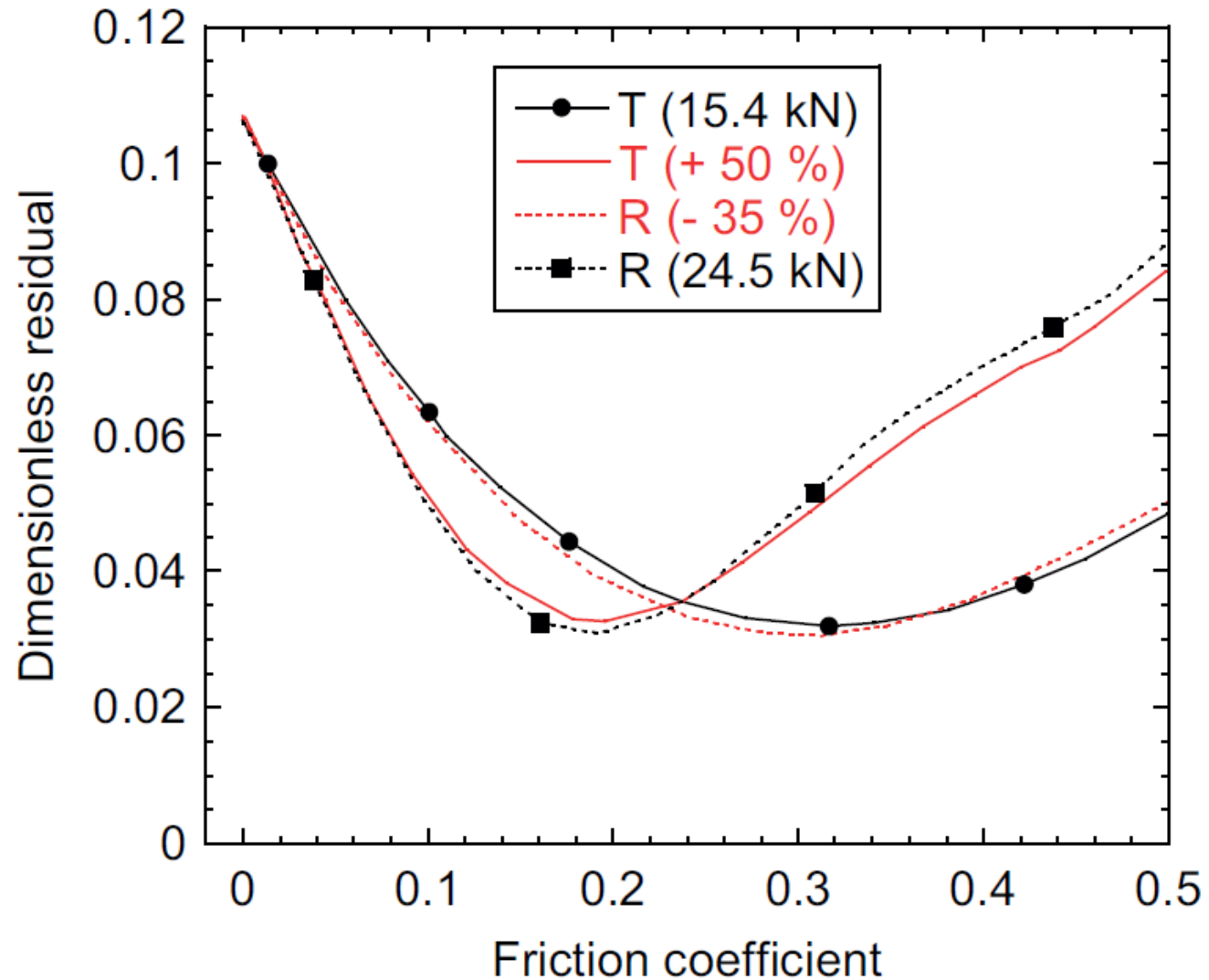
- Measured field $\underline{\mathbf{u}}_{meas}(\underline{\mathbf{x}})$
- Computed field $\underline{\mathbf{u}}_{comp}(\underline{\mathbf{x}})$
- Rigid body motions $\underline{\mathbf{u}}_{rbm}(\underline{\mathbf{x}}) = \underline{\mathbf{u}}_0 + \underline{\boldsymbol{\omega}} \times \underline{\mathbf{x}}$
- Validation residuals

$$\rho = \min_{f, \underline{\mathbf{u}}_0, \underline{\boldsymbol{\omega}}} \sum_i \left(\underline{\mathbf{u}}_{meas}(\underline{\mathbf{x}}_i) - \underline{\mathbf{u}}_{comp}(\underline{\mathbf{x}}_i) - \underline{\mathbf{u}}_0 - \underline{\boldsymbol{\omega}} \times \underline{\mathbf{x}}_i \right)^2$$

Full-Field Validation



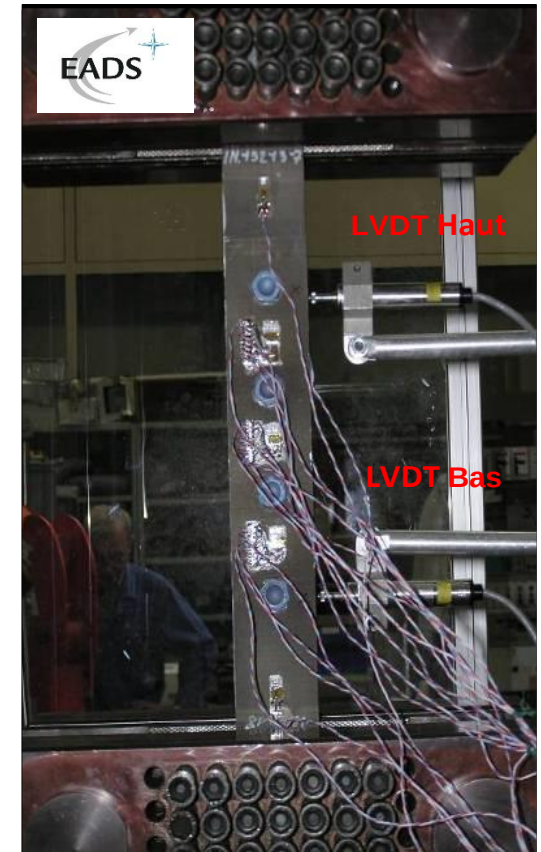
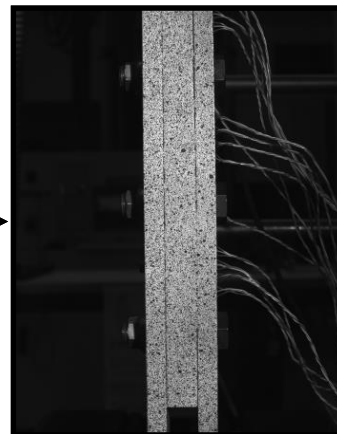
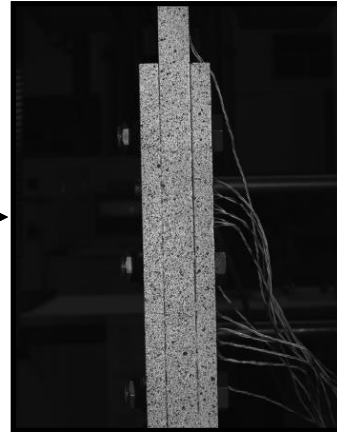
Full-Field Validation



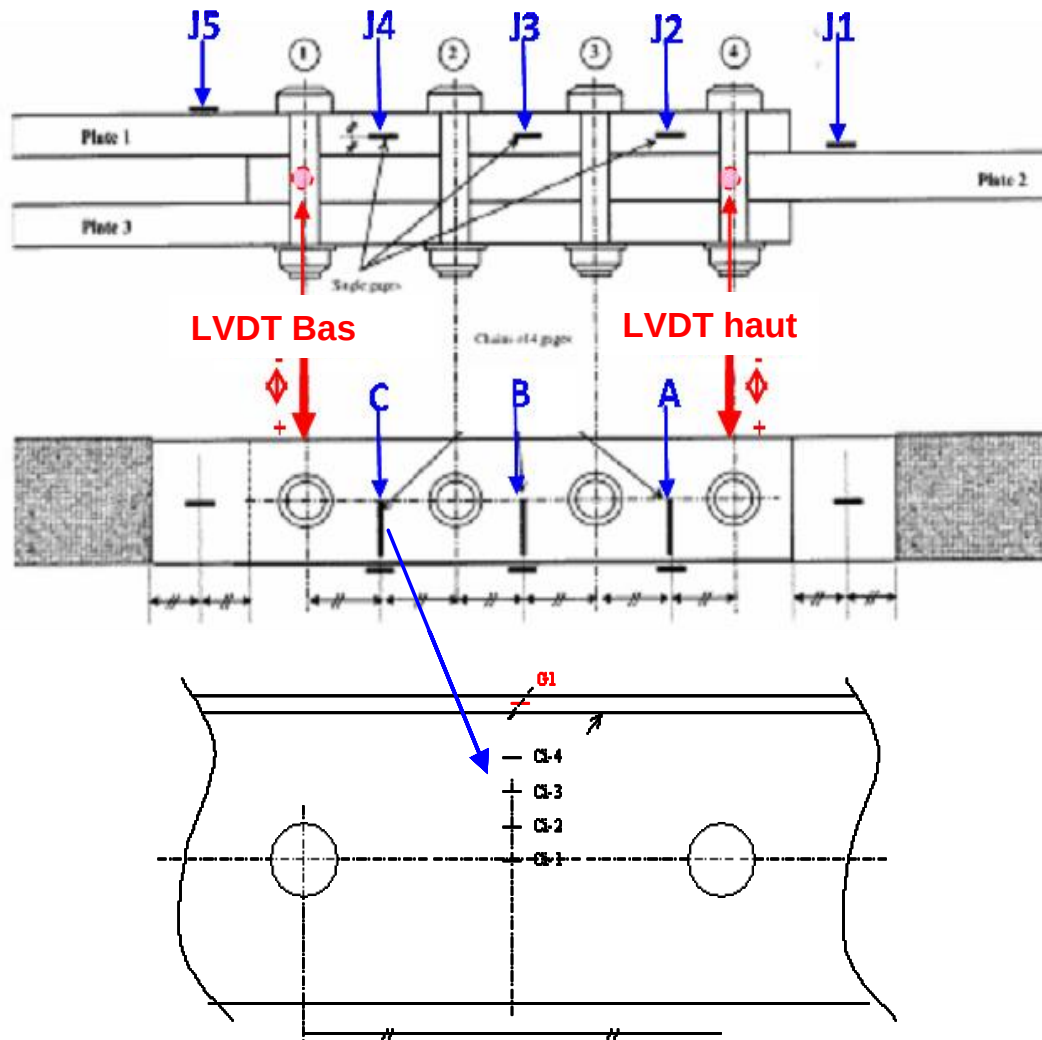
Outline

- Introduction
- Double lap joint w/ single bolt
- **Load transfer in 4-bolt assembly**
- Conclusion & perspectives

Extension to Multiple Fastening



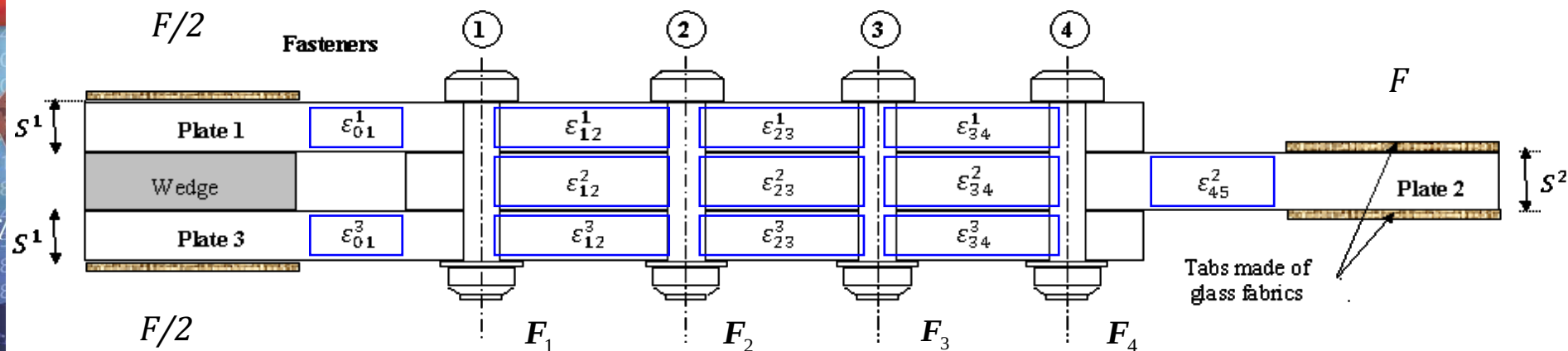
Strain Gauges



17 gauges :

- 14 on the face
- 3 on the edge

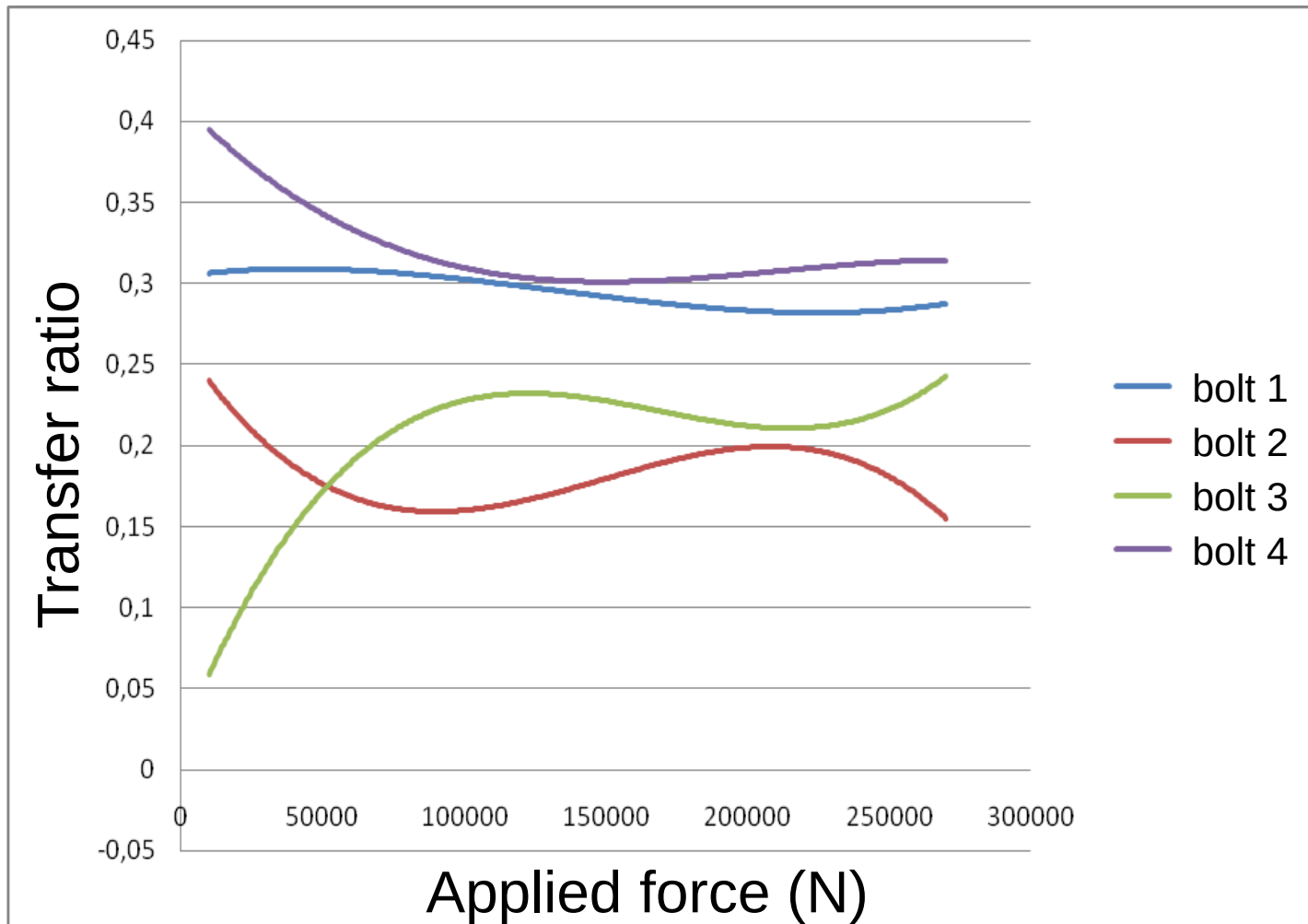
Transfer Ratio?



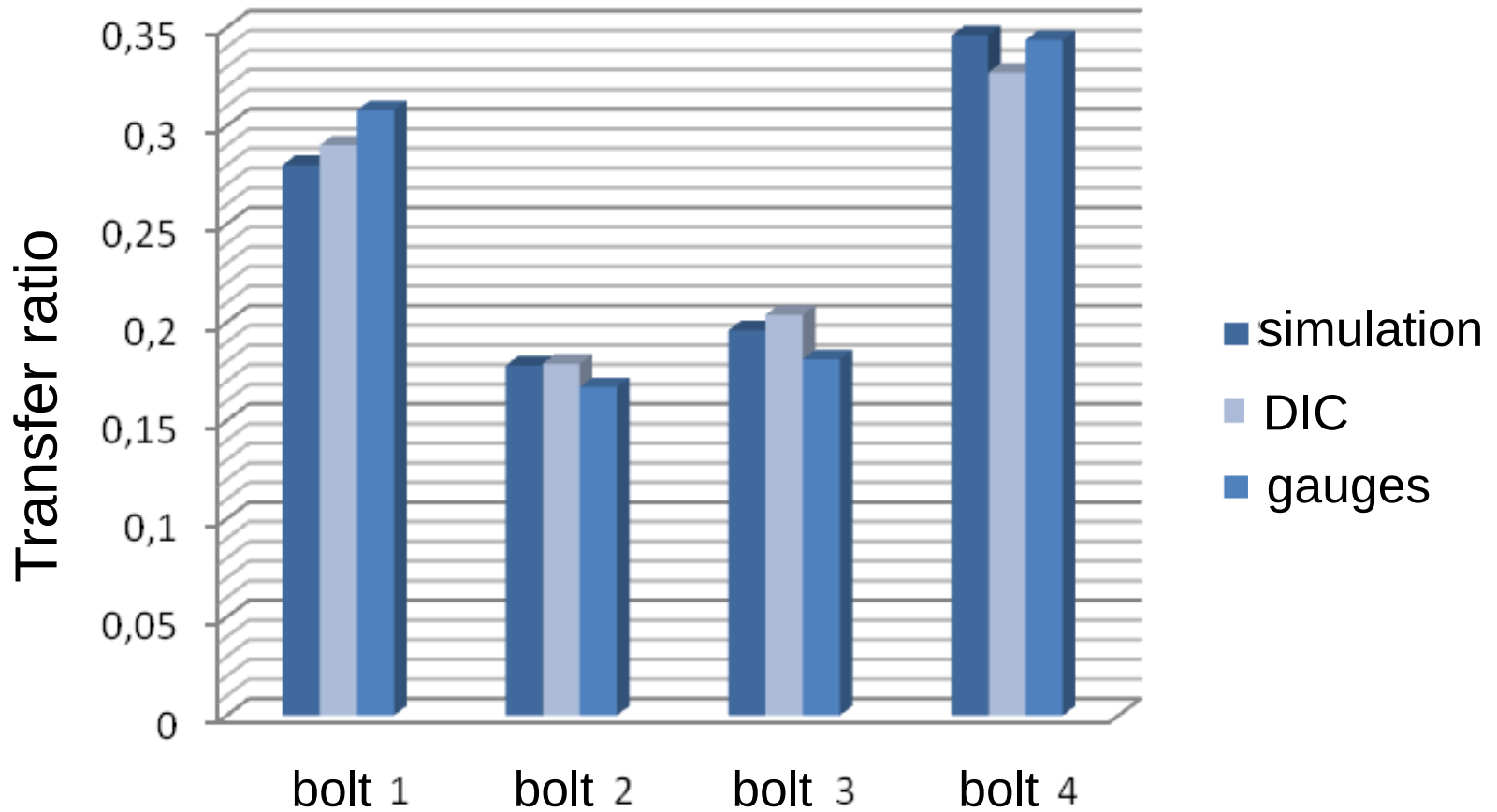
$$\begin{cases} F = E^1 S^1 (\epsilon_{01}^1 + \epsilon_{01}^3) \\ F - (F_1^1 + F_1^3) = E^1 S^1 (\epsilon_{12}^1 + \epsilon_{12}^3) \\ F - (F_1^1 + F_1^3 + F_2^1 + F_2^3) = E^1 S^1 (\epsilon_{23}^1 + \epsilon_{23}^3) \\ F - (F_1^1 + F_1^3 + F_2^1 + F_2^3 + F_3^1 + F_3^3) = E^1 S^1 (\epsilon_{34}^1 + \epsilon_{34}^3) \\ F = F_1 + F_2 + F_3 + F_4 \end{cases}$$

$$\begin{cases} F = E^2 S^2 \epsilon_{45}^2 \\ F_1^2 + F_2^2 + F_3^2 = E^2 S^2 \epsilon_{34}^2 \\ F_1^2 + F_2^2 = E^2 S^2 \epsilon_{23}^2 \\ F_1^2 = E^2 S^2 \epsilon_{12}^2 \\ F = F_1 + F_2 + F_3 + F_4 \end{cases}$$

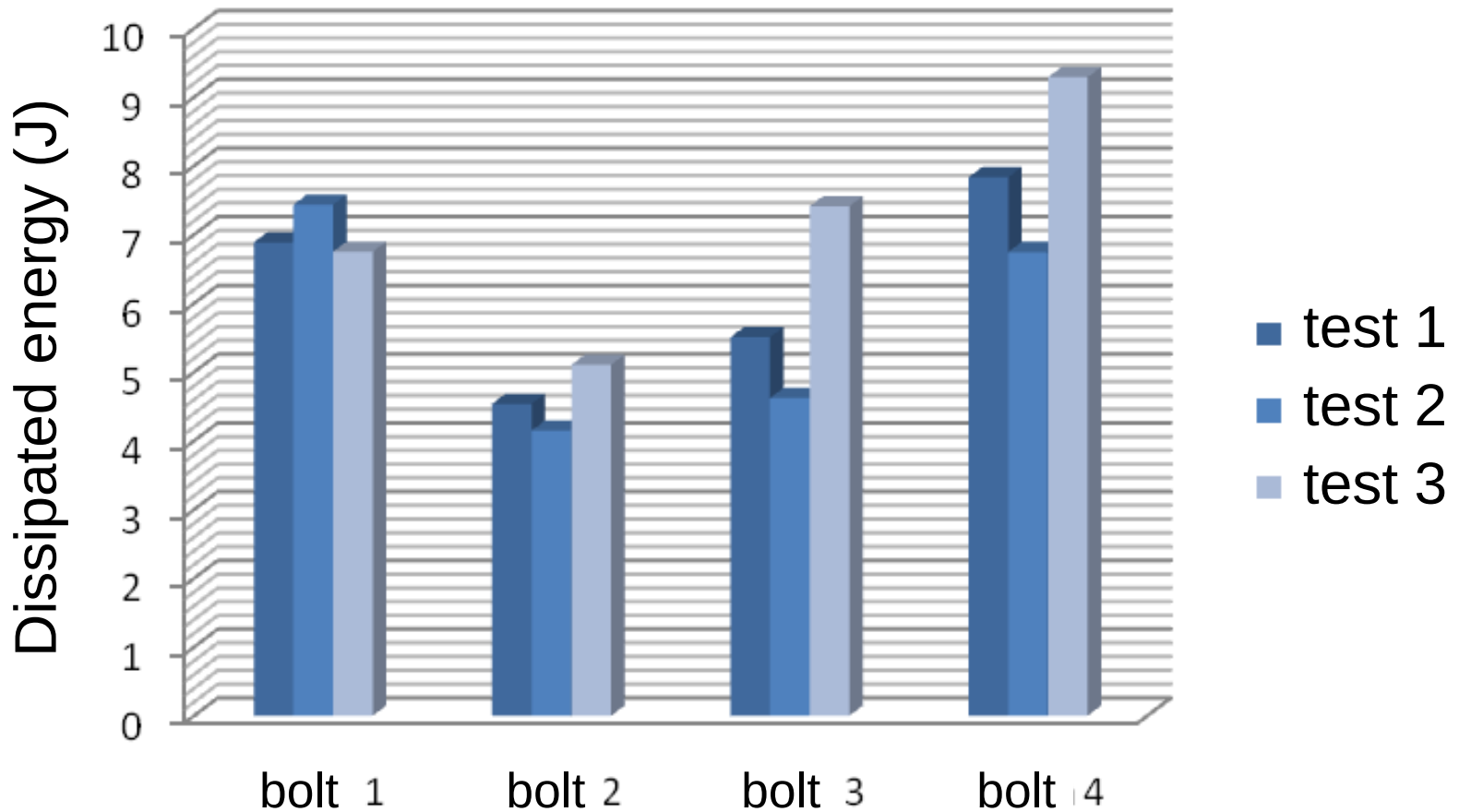
Transfer Ratio vs. Applied Force



Validation



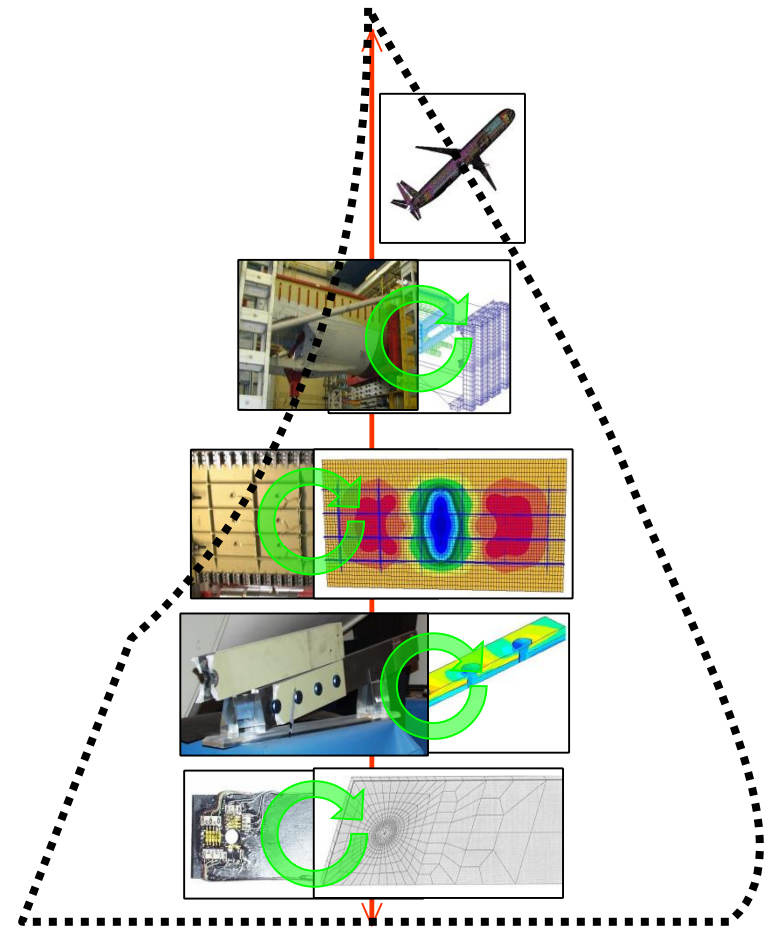
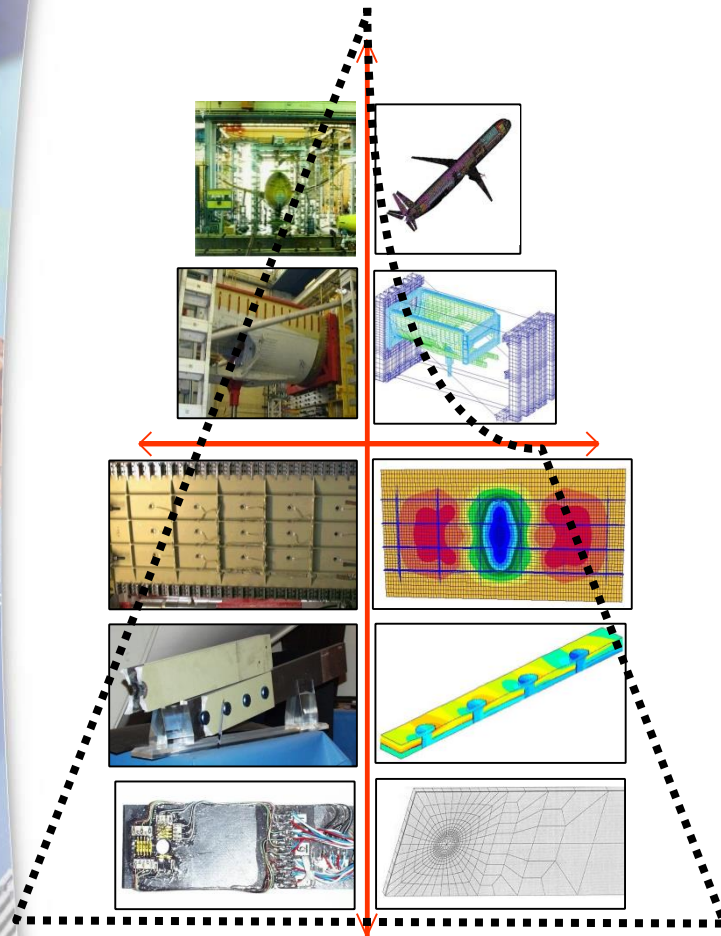
Dissipated Energy



Conclusion

- Improvement of experimental protocol
- In spite of difficult context and low image definition, DIC has shown its ability to provide quantitative information in analysis of single and multi-bolt assemblies
- Evolution of friction coefficient and transfer ratios
- Calculation of dissipated energy

Outlook



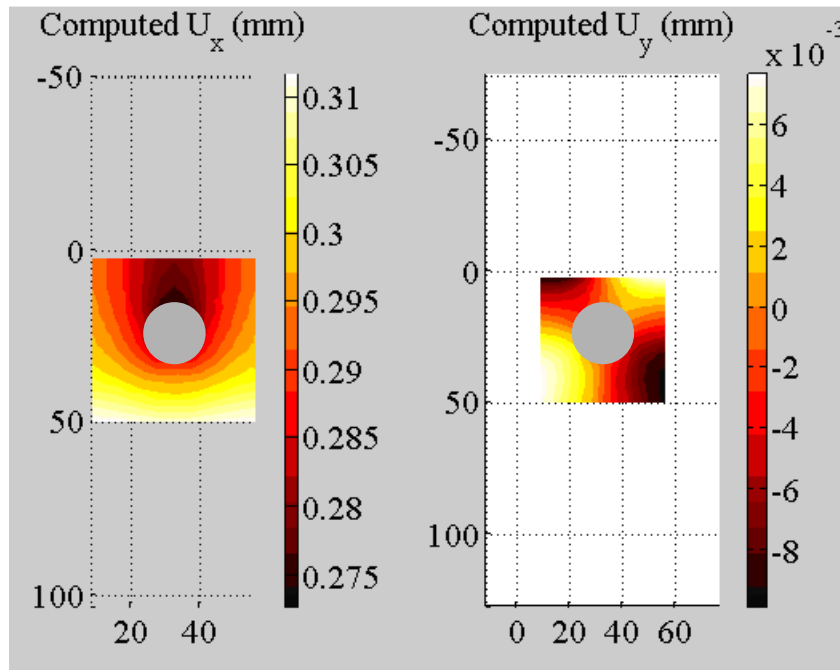
**Test / simulation
interactions**

Merci de votre attention !

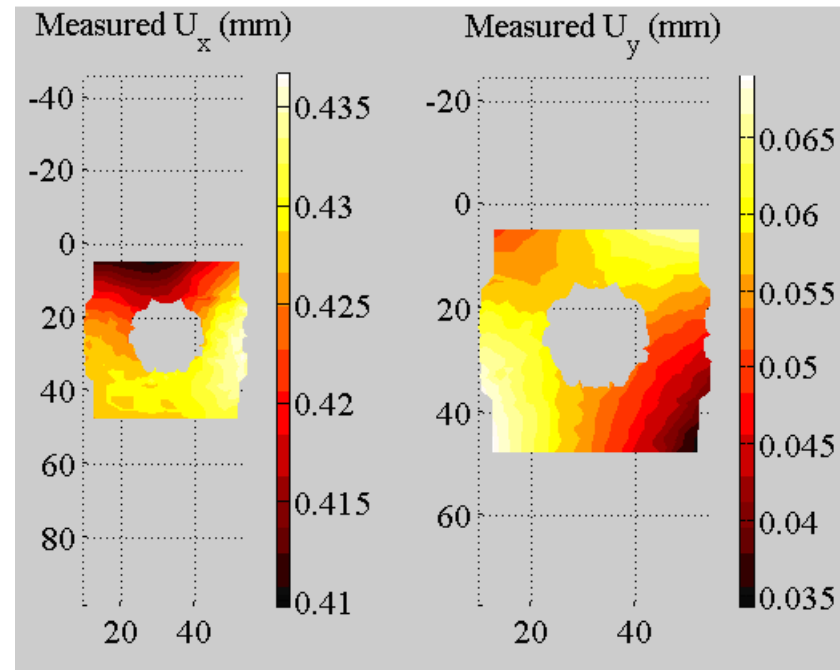


Computed / measured fields

COFAST*



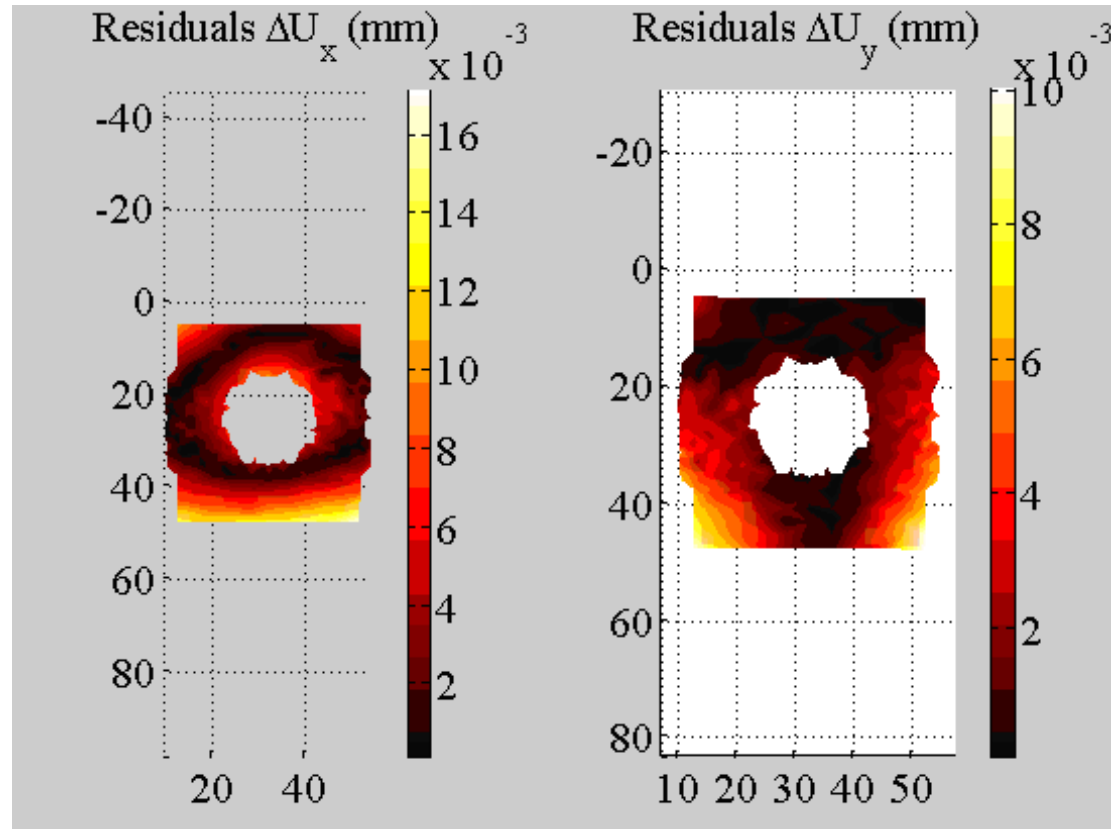
Q4-DIC**



*[Champaney *et al.*, 1999, *Comput. Struct.* 73 249-266]

**[Besnard *et al.*, 2006, *Exp. Mech.* 46 789-803]

Identification residual



$T_f = 6000 \text{ N}$